

Game-based abstraction of Markov decision processes

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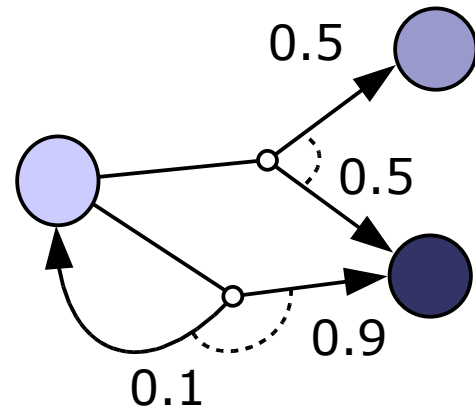
QEST'06

Overview

- Markov decision processes (MDPs)
- Simple stochastic games (SSGs)
- Abstraction of MDPs using SSGs
- Case study: Zeroconf protocol

Markov decision processes (MDPs)

- Model both **probabilistic** and **nondeterministic** choice
 - concurrency: parallel composition of stochastic components
e.g. communication protocols, randomised algorithms, ...
 - unknown environment: e.g. probabilistic security protocols
- MDP $M = (S, \text{Steps})$ where:
 - set of states S
 - **Steps** : $S \rightarrow 2^{\text{Dist}(S)}$
mapping from states to sets of probability distributions



Probabilistic verification of MDPs

- Formal analysis of **quantitative** properties of MDPs
 - probabilistic extensions of temporal logic, e.g. PCTL
- **Adversaries (also known as schedulers, policies)**
 - adversary **A** = resolution of all nondeterminism in MDP
 - **A** is a mapping from finite paths to probability distributions
- **Probabilistic reachability (for a set of goal states **F**)**
 - $p_A(F)$ = probability of reaching states **F** under adversary **A**
 - **minimum/maximum** probabilities over all adversaries
 - $p_{\min}(F) = \inf_A p_A(F)$
 - $p_{\max}(F) = \sup_A p_A(F)$

Probabilistic verification of MDPs...

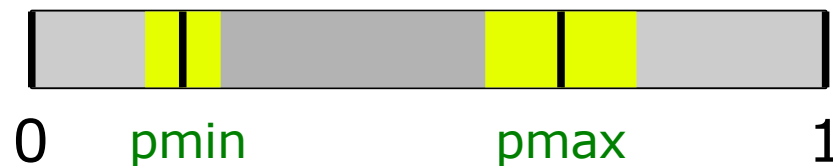
- Analysis of best/worst-case scenarios for MDP:
 - “maximum probability of an error occurring”
 - “minimum probability of termination within T seconds”
 - “maximum expected time for completion”
 - “minimum expected number of rounds required”
- Probabilistic model checking algorithms
 - solution of linear optimisation problems
 - iterative numerical methods (dynamic programming)
 - efficient symbolic implementations, tools (e.g. PRISM)
 - but... state space explosion still a major issue

Abstraction

- Very successful in (non-probabilistic) model checking
- Construct abstract model M' of concrete model M
 - details not relevant to property of interest removed
 - merge states according to a given partition of state space
 - e.g. from set of predicates (predicate abstraction)
- Counterexample guided abstraction and refinement
 - conservative: satisfaction in M' implies satisfaction in M
 - converse does not hold, but...
 - information from model checking process (counterexample) can be used to refine the abstraction

Abstraction of MDPs

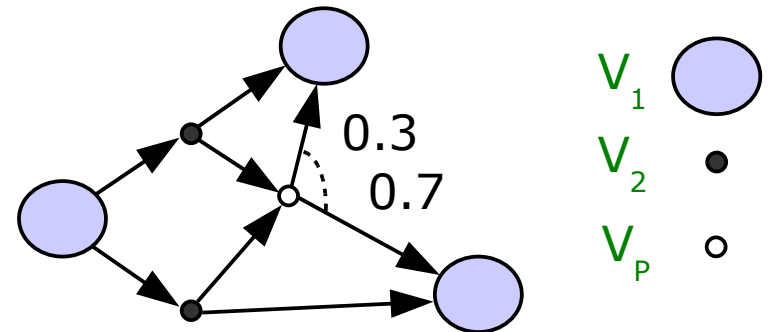
- Abstraction increases degree of nondeterminism
 - minimum probability will be lower, and maximum higher
- Key idea: separate two forms of nondeterminism
 - (a) from abstraction and (b) from original MDP
- Generate separate lower/upper bounds for min/max



- Gives quantitative measure of utility of abstraction
 - if lower/upper bounds not close enough...
 - refine abstraction and repeat

Simple stochastic games (SSGs)

- Simple stochastic two-player games [Condon]
- Game $G = ((V, E), v_{\text{init}}, (V_1, V_2, V_p), \delta)$
 - (V, E) is a finite directed graph
 - v_{init} is the initial vertex
 - (V_1, V_2, V_p) is a partition of V :
'player 1', 'player 2', 'probabilistic'
 - $\delta : V_p \rightarrow \text{Dist}(V)$ is a probabilistic transition function
- Execution of G : successor in each vertex chosen...
 - by player 1/2 for V_1/V_2 vertices
 - at random (δ) for V_p vertices



Analysis of SSGs

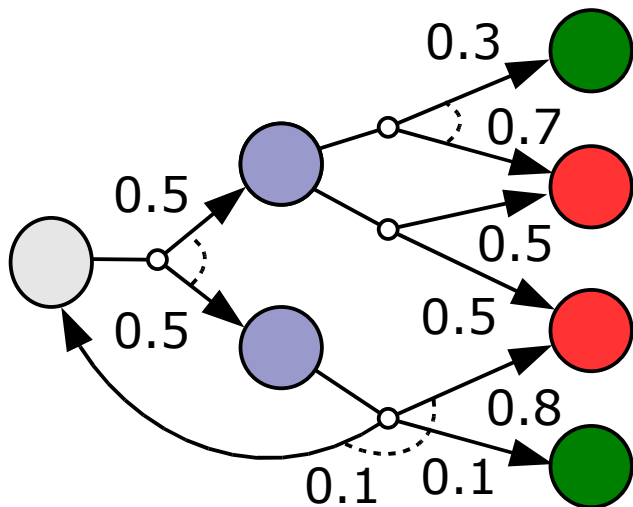
- Probabilistic reachability of vertex goal set F
 - strategies a_1, a_2 are resolutions of choices for players 1, 2
 - $p_{a_1, a_2}(F)$ = probability of reaching F under strategies a_1, a_2
 - optimal probabilities for player 1 and player 2:
 - $\sup_{a_1} \inf_{a_2} p_{a_1, a_2}(F)$ and $\sup_{a_2} \inf_{a_1} p_{a_1, a_2}(F)$
 - computable via simple iterative methods, similar to MDPs

Abstract MDP

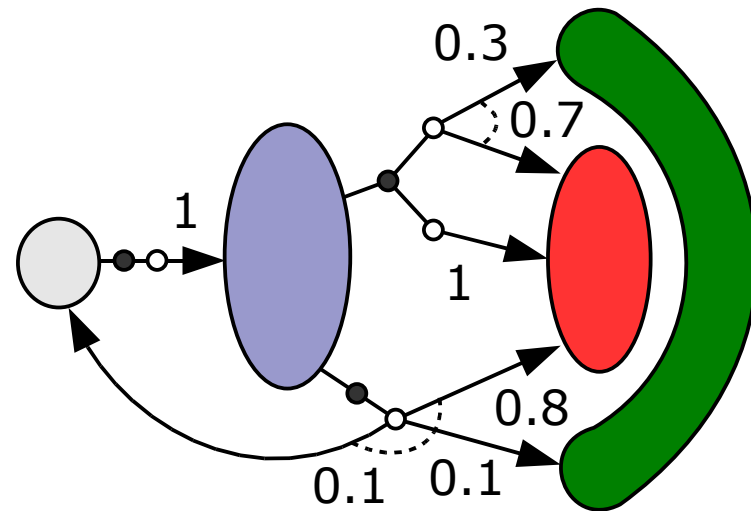
- **Abstract MDP is a simple stochastic game**
 - based on a partition P of MDP state space S
 - V_1 states are elements of P (subsets of S)
 - V_2 states are sets of prob. distributions (“states of MDP”)
 - V_p states are single probability distributions (now over V_1)
 - strict alternation between V_1, V_2, V_p vertices
- **Player 1 controls nondeterminism from abstraction**
 - selects a state of the original MDP from a subset of S (in P)
- **Player 2 controls nondeterminism from original MDP**
 - selects a single probability distribution from a set

Simple example

Original MDP



Abstract MDP
(simple stochastic game)



Analysis of abstract MDP

- For set of goal states/vertices F in MDP/SSG...
- Compute lower/upper bounds for $p_{\min}(F)$, $p_{\max}(F)$ on MDP using abstract MDP (SSG):

$$\inf_{a_1, a_2} p_{a_1, a_2}(F) \leq p_{\min}(F) \leq \sup_{a_1} \inf_{a_2} p_{a_1, a_2}(F)$$

$$\sup_{a_2} \inf_{a_1} p_{a_1, a_2}(F) \leq p_{\max}(F) \leq \sup_{a_1, a_2} p_{a_1, a_2}(F)$$

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min/max reachability probabilities for original MDP

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optimal probabilities for player 1, player 2 in abstract MDP

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equivalent to normal analysis of min/max probs for MDP
(but performed on abstract MDP)

Implementation

- **Prototype implementation in Java**
 - construction of SSGs (abstract MDPs)
 - iterative numerical analysis of SSGs
- **Based on reduction of full original MDP**
 - constructed and exported in PRISM

Case study: Zeroconf protocol

- Decentralised self configuration of local IP addresses
 - new node joining network of N existing nodes, M addresses
 - **probabilistic**: based on random selection of IP address
 - **nondeterministic**: concurrency from scheduling, unknown message propagation delays (different range for each node)
- **Abstraction**
 - abstract M IP addresses to 2 values: in-use/fresh
 - abstract messages: just store type of message, not sender
 - consequently, we lose information about message timings
 - provided by user in terms of PRISM model variables
 - see paper for more details

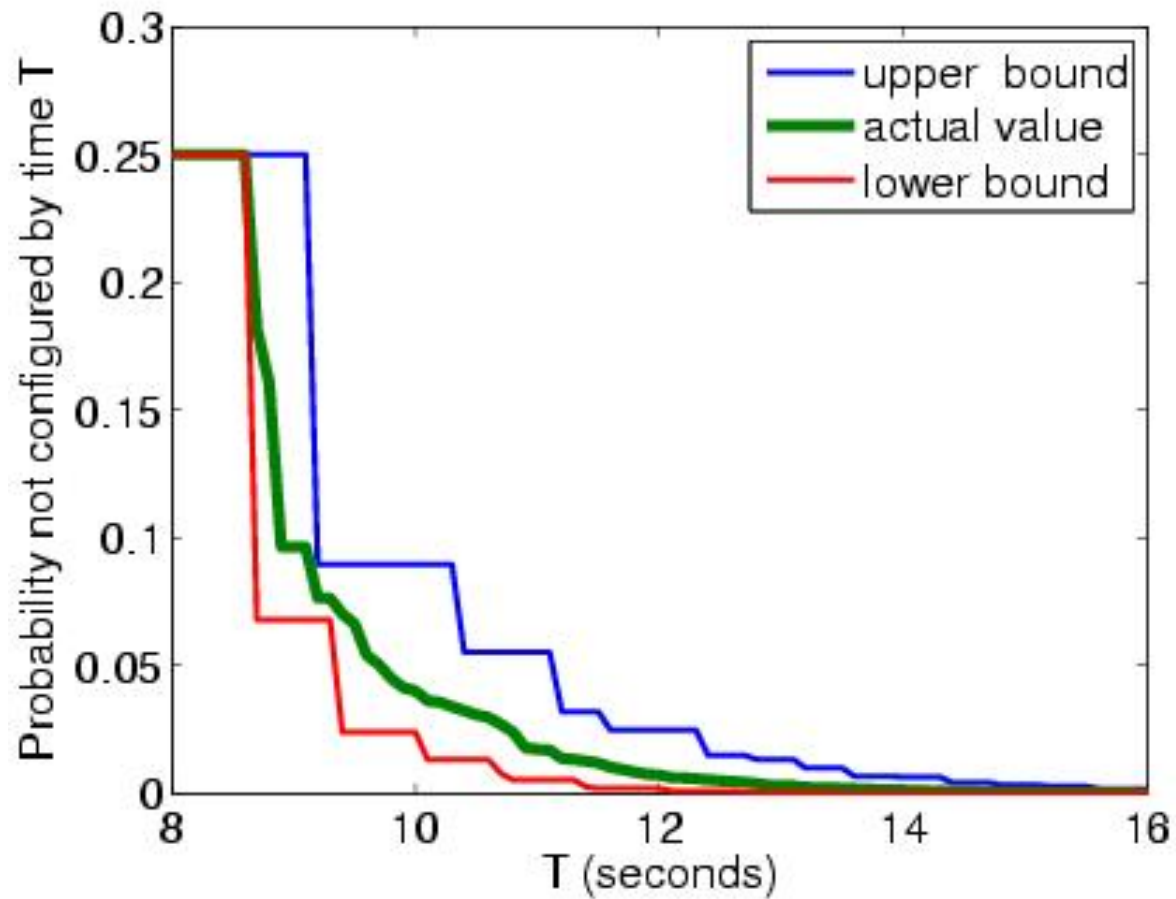
Results

- Substantial reduction in model size (MDP vs. SSG)

N	States		Transitions	
	MDP	Abs	MDP	Abs
4	26,121	737	50,624	1,594
5	58,497	785	139,104	1,678
6	145,801	833	432,944	1,762
7	220,513	857	614,976	1,806
8	432,185	881	1,254,480	1,850

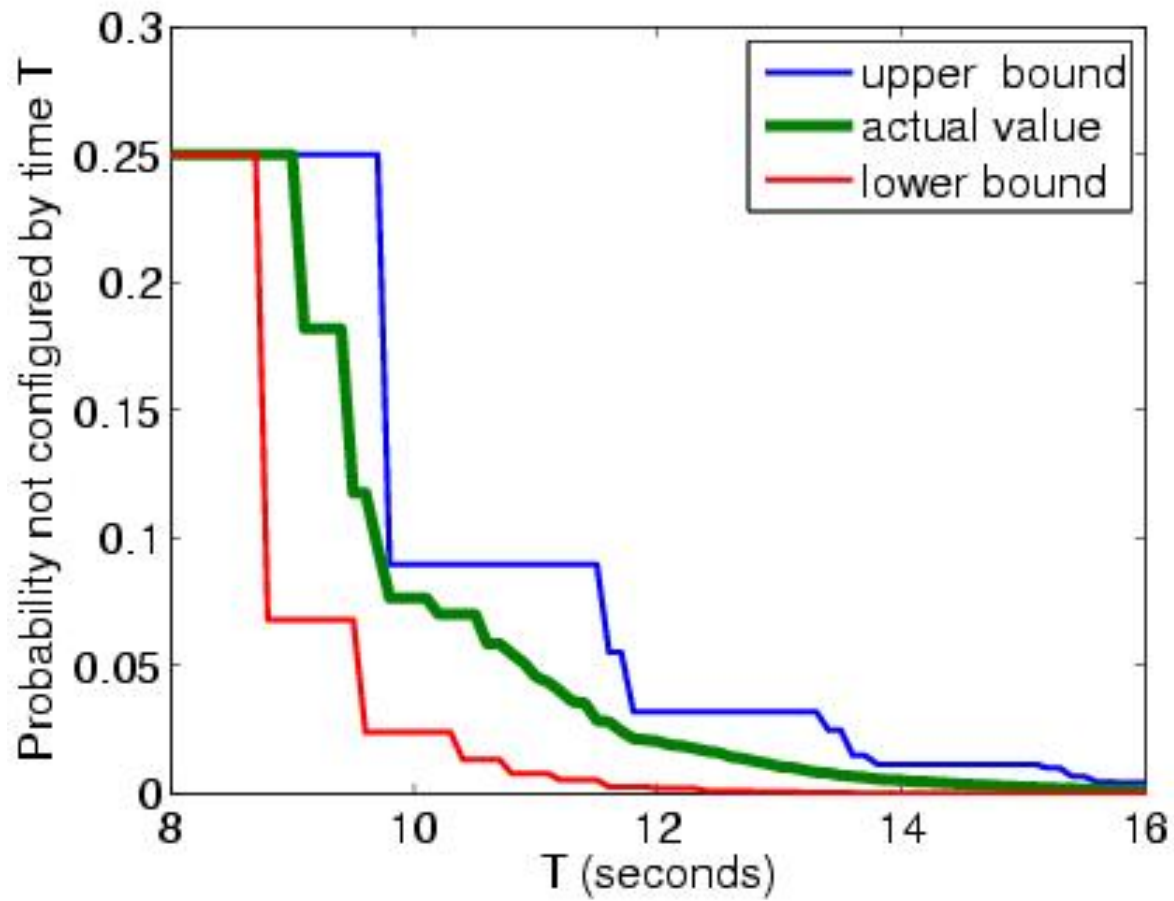
Results

- Minimum probability not configured by time T:



Results

- Maximum probability not configured by time T:



Conclusions

- **Novel abstraction approach for MDPs using SSGs**
 - separation of nondeterminism from MDP/abstraction
 - both lower/upper bounds for min/max probabilities
 - quantitative measure of utility of abstraction
 - promising results: model reduction, quantitative results
- **Future work**
 - perform abstraction at PRISM language level (not on MDP)
 - efficient symbolic implementation of SSG algorithms
 - automatic/semi-automatic generation of partitions
 - more case studies, comparison with related work